Unit: Rotational Statics & Dynamics

NGSS Standards/MA Curriculum Frameworks (2016): N/A

AP® Physics 1 Learning Objectives/Essential Knowledge (2024): 5.4.A, 5.4.A.1,

5.4.A.2, 5.4.A.3, 5.4.B, 5.4.B.1, 5.4.B.2

Mastery Objective(s): (Students will be able to…)

• Calculate the moment of (rotational) inertia of a system that includes one or more masses at different radiï from the center of rotation.

Success Criteria:

- Correct formula for moment of inertia of each basic shape is correctly selected.
- Variables are correctly identified and substituted correctly into the equation.
- Algebra is correct and rounding to appropriate number of significant figures is reasonable.

Language Objectives:

• Explain how an object's moment of inertia affects its rotation.

Tier 2 Vocabulary: moment

Labs, Activities & Demonstrations:

• Try to stop a bicycle wheel with different amounts of mass attached to it.

Notes:

inertia: the tendency for an object to continue to do what it is doing (remain at rest or remain in motion).

rotational inertia (or angular inertia): the tendency for a rotating object to continue rotating.

moment of inertia (*I*): a quantitative measure of the rotational inertia of an object. Moment of inertia is measured in units of $kg·m²$.

Inertia in linear systems is a fairly easy concept to understand. The more mass an object has, the more it tends to remain at rest or in motion, and the more force is required to change its motion. *I.e.,* in a linear system, inertia depends only on mass.

center of mass: the point where all of an object's mass could be placed without changing the results of any forces acting on the object. (See *Center of Mass*, starting on page 268.)

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The moment of inertia of any object about an axis through its center of mass is always the minimum moment of inertia for any axis in that direction in space.

The moment of inertia about another axis that is parallel to the axis through the center of mass, at a distance \vec{r} from the object's center of mass, is given by the equation:

$$
I_{\text{parallel axis}} = I_{\text{cm}} + mr^2
$$

You would use the parallel axis theorem if you have a mass that is forced to rotate around some axis other than its center of mass, such as the following example:

This can be demonstrated by spinning a "bicycle wheel" with handles, then attaching a 0.5-kg mass to the outside of the wheel and spinning it again. The new center of mass of the system is no longer where the handles are; when the wheel is spun, it requires a significant amount of force (*i.e.,* more than students are capable of applying) to keep it from wobbling. This is why car wheels or washing machines that are "out of balance" wobble in ways that can cause significant damage.

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